Read this document carefully before using this device. The guarantee will be expired by damaging of the device if you don't attend to the directions in the user manual. Also we don't accept any compensations for personal injury, material damage or capital disadvantages.

## ENDA EI2041 PROGRAMMABLE INDICATOR

Thank you for choosing ENDA EI2041 INDICATOR.
$35 \times 77 \mathrm{~mm}$ sized.
4 digits display.
Display scale can be adjusted between -1999 and 4000.
Decimal point can be adjusted between 1st. and 3rd. digits.
Measurement unit can be displayed.
Selectable four different standard input types ( $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}, 0-1 \mathrm{~V}, 0-10 \mathrm{~V}$ ).

- User can calibrate the device according to specified input type.

Sampling time can be adjusted in four steps.
Stores maximum and minimum measurement values.
Maximum and minimum values can be stored and displayed.
Two relay output for control and alarm (Optional).
Control option below and above set value.
Selectable independent, deviation and band alarm.


Sensor supply output (Optional).
RS485 Modbus RTU communication protocol feature (Optional).

- CE marked according to European standards.



## TECHNICAL SPECIFICATIONS

## ENVIRONME NTAL CONDITIONS

| Ambient/storage temperature | $0 \ldots+50^{\circ} \mathrm{C} /-25 \ldots+70^{\circ} \mathrm{C}$ (with no icing). |
| :--- | :--- |

Max. relative humidity $80 \%$ Relative humidity for temperatures up to $31^{\circ} \mathrm{C}$, decreasing linearly to $50 \%$ at $40^{\circ} \mathrm{C}$.
Rated pollution degree Height According to EN 60529 Front panel : IP65 Rear panel : IP20
Max. 2000m.
Do not use the device in locations subject to corrosive and flammable gases.
ELECTRICAL CHARACTERISTICS

| Supply | 230 V AC 110 V AC $+\% 10-\% 20,12 / 24 \mathrm{~V}$ AC $\pm \% 10,50 / 60 \mathrm{~Hz}$ or $9-30 \mathrm{~V}$ DC /7-24V AC $\pm \% 10$ SMPS optional. |  |  |  |
| :---: | :---: | :---: | :---: | :---: |
| Power consumption | Max. 7VA. |  |  |  |
| Wiring | $2.5 \mathrm{~mm}^{2}$ screw-terminal connections. |  |  |  |
| Date retention | EEPROM (Min. 10 years). |  |  |  |
| EMC | EN 61326-1: 2013. |  |  |  |
| Safety requirements | EN 61010-1: 2010 (Pollution degree 2, overvoltage category II, measurement category I).$\square$ EI2041 cannot be used if measurement category II, III or IV is required. |  |  |  |
| Input type | Measurement range |  | Measurement accuracy | Input empedan |
|  | Min. | Max. |  |  |
| $0-1 \mathrm{~V}$ DC voltage | OV | 1.1 V | $\pm 0,5 \%$ (of full scale) | Approx. 100k $\Omega$ |
| $0-10 \mathrm{~V}$ DC voltage | OV | 12 V | $\pm 0,5 \%$ (of full scale) | Approx. $100 \mathrm{k} \Omega$ |
| $0-20 \mathrm{~mA} \mathrm{DC} \mathrm{current}$ | OmA | 25 mA | $\pm 0,5 \%$ (of full scale) | Approx. $10 \Omega$ |
| 4-20mA DC current | OmA | 25 mA | $\pm 0,5 \%$ (of full scale) | Approx. $10 \Omega$ |

While the current measuring mode, input impedance becomes $10 \Omega$. Therefore, in current mode, the device must not be connected any voltage input. Otherwise, the device is broken. While the device is running in the voltage measurement mode and if required to change to current measurement mode, then firstly the voltage inputs mustbe removed and after that, inputtype mustbe changed to one of the currentmeasurement modes.

## OUTPUTS

| Sensor power supply | All sensor supply outputs maximum 50 mA . (Regulated and isolated). |
| :--- | :--- |
| O | R |


| Out | Relay: $250 \mathrm{~V} \mathrm{AC}$,8 A (resistive load), NO |
| :--- | :--- |


| Alarm | Relay: $250 \mathrm{~V} \mathrm{AC}, 8 \mathrm{~A}$ (resistive load), NO |
| :--- | :--- |

Life expectancy for relay Mechanical 30. Mio. operation; 100.000 operation at 250 V AC, 8 A resistive load
CONTROL

| Control type | Double set-point and alarm control. |
| :--- | :--- |

Control algorithm
On-Off control.
Hysteres is Adjustable between 1 ... 200.

## HOUSING

## Housing type

Dimentions
Weight
Weight
Enclosure material
Suitable for flush-panel mounting according to DIN 43700.
W77xH35xD71mm.
Approx. 350 g (after packaging)
Self extinguishing plastics.
While cleaning the device, solvents (thinner, gasoline, acid etc.) or corrosive materials must not be used.


## DIMENSIONS



## To removing the mounting clamps :

- Push the flush-mounting
clamps in direction 1
- Pull out the clamps in direction 2.



## Note:

1) While panel mounting, additional distance required
for connection cables should be considered.
2) Panel thickness should be maximum 7 mm .
3) If there is no 60 mm free space at back side of the
device, it would be difficult to remove it from the panel.

## CONNECTION DIAGRAM

ENDA EI2041 is intended for installation in control panels. Make sure that the device is used only for intended purpose. The shielding must be grounded on the instrument side. During an installation, all of the cables that are connected to the device must be free of energy. The device must be protected against inadmissible humidity, vibrations, severe soiling. Make sure that the operation temperature is not exceeded. All input and output lines that are not connected to the supply network must be laid out as shielded and twisted cables. These cables should not be close to the power cables or components. The installation and electrical connections must be carried on by a qualified staff and must be according to the relevant locally applicable regulations.

ENDA industrial electronics sn: xxxxxxxxx E12041-230 programmable indicator $\quad \||||||||||||||||||||||||| |$



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 ROHS
 $0.4-0.5 \mathrm{Nm}$.

Note: 1) Mains supply cords shall meet the requirements of IEC 60227 or IEC 60245
2) In accordance with the safety regulations, the power supply switch shall bring the identification of the relevant instrument and it should be easily accessible by the operator.

## Displaying the Measurement Unit



In "Running Mode", if ser keys are pressed together for 3 seconds, measurement unit appears. See Ún it parameter for programming.


Resetting Maximum and Minimum Measurement Values

| 571 | $\begin{aligned} & \text { Measurement } \\ & \text { Value } \end{aligned} \rightarrow \stackrel{\text { ser }}{r E S}$ | In "Running Mode", if key pressed for 2 seconds, maximum and minimum measurement values become equal to the measured value at current time and the $\square$ <br> res message appears on display. |
| :---: | :---: | :---: |
| Locking and Unlocking |  |  |
| 571 | $\begin{aligned} & \text { Measurement } \\ & \text { Value } \end{aligned} \rightarrow \stackrel{\text { SET }}{\mathrm{Loc}}$ | Keys are locked. If $\square$ keys are pressed together for 2 seconds, $L$ oc message appears and keys are locked. For unlocking, $\square$ keys are pressed together for 2 seconds, uni message Keys are unlocked. appears and keys are unlocked. If one of the keys is pressed while the device locked, Loc message appears on display. |

## Setting Up User Calibration Values

No calibration required if the standard inputs ( $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}, 0-1 \mathrm{~V}$ and $0-10 \mathrm{~V}$ ) are used. CRL.E Parameter should be set as U. inP if no standard input used. In user menu, if key is pressed for 7 seconds, L.inP message appears on display and calibration menu is entered.
Voltage or current which are corresponds to $L$ SLL parameter is applied to device input and ${ }^{\text {ser }}$ key is pressed. If operation is success, Succ message appears on display and proceeding to the next step.
In this step, while $h, 4, \mathrm{PP}$ message displayed, voltage or current which are corresponds to $L S[L$ parameter is applied to device input and ser is pressed. If operation is success, Succ then C.End message appears on display, calibration process is completed and the device will start running according to the new calibration values.

## ERROR MESSAGES \& DESCRIPTIONS !

Error conditions and descriptions are listed below.

* If voltage or current is difference and lower than half of full scale between $\mathrm{H} ., \mathrm{n} \mathrm{P}$ and L . ınP voltage or current.
* If excessive high-low input current or voltage is applied
* If an error occurs during L . $\mathrm{InP}^{\mathrm{P}}$ calibration, $\operatorname{Err} \boldsymbol{I}$ message appears on display
* If an error occurs during $H ., \cap P$ calibration, $E r r \mathcal{Z}$ and $\mathcal{L} \cdot E r r$ message appears on display.
* If user calibration is not applied before and an error occurs during calibration process, device runs according to standard calibration values.
* If user calibration is applied before and an error occurs during calibration process, device runs according to previous user calibration values.


## Changing Parameters

If \begin{tabular}{l}
keys are pressed together for 2 seconds, $P$, message appears and user menu entered. Then in user menu, first parameter's is displayed. <br>

When a parameter selected, if | key is pressed selected parameter value appears and displayed parameter can be changed by |
| :--- |
| operation is performed for 3 seconds after the parameter value is being displayed or ser key is pressed, parameter name will be shown again. While |
| parameter name displayed, |$\quad$ keys are pressed together, returned to "Running Mode" without waiting period.

\end{tabular}

## Hidden Menu

## Programming Mode

If $\square$ key is pressed for 7 seconds $P 己{\underset{y y}{s e x}}_{\text {message appears on the display and hidden menu is entered. Selected }}^{\text {ser }}$ parameter values can be displayed with $\square$ key and canged with $\triangle$ keys. Accessing to the parameters and storing functions are as in the user menu. All parameters can be accessed from this menu.

## Parameter Transfer Between Menus

If $\square$ keys are pressed together for 2 seconds, parameter transferred to user menu. In this way up to 12 parameters can be transferred to the user menu.
In user menu, if ${ }^{\text {ssir }}$ keys are pressed together for 2 seconds, parameter is removed from user menu. When a parameter is displayed in the user menu, mA LED lights up in the hidden menu.


Setting Up Measurement Unit (U' $n$ it ) Parameters
If pressed ${ }^{\text {ser }}$ key in U' $\operatorname{in}$, $\ell$ parameter, related digit blinks on display. For desired number, letter or symbol is adjusted by pressing the $\square$ key for related digit. For setting up other digits key is pressed. When parameter setting process is completed, by pressing ${ }^{\text {ser }}$ key or no key is pressed for 3 seconds without pressing any key, parameters can be saved.



PARAMETER LIST

| CONFIGURATION PARAMETERS |  | Initial Value |
| :---: | :---: | :---: |
| 1. $¢$ P | Input type selection. ( $0-20 \mathrm{~mA}, 4-20 \mathrm{~mA}, ~ 5-i \mathrm{~V}, ~ 5-10 \mathrm{~V})$ | 0-10 |
| ${ }^{\text {d }}$ SP.L | Indicator configuration. (Prc 5 : Process value, Pr.ún : 4 Seconds process value, 2 Seconds Ún it value.) | Pre 5 |
| rRtE | Measurement ranges. <br> FRSt : Average of 1 measurement value is gathered in 200 msec . <br> SLo. i: Average of 4 measurement value is gathered in 200 msec . <br> 5 LOL : Average of 8 measurement value is gathered in 200 msec . <br> $5 \mathrm{Lo3}$ : Average of 16 measurement value is gathered in 200 msec . | SLo.i |
| HoLd | Indicator holding parameter. ( $n o n E$ : instant measurement value, Lo. : minimum value, H , : maximum value is displayed.) | nonE |
| Un it | Measurement value. (Desired measurement value for unit selection). | nonE |
| LRL.L | Calibration type. ( S.ınP: Standard input type, U', ınP: User defined input type selection ). | 5. 1 mP |
| d.Pnt | Decimal point selection. ( Adjustable between the 1th. and 3rd digits ). | 0 |
| L.5CL | Lower scale value. ( Adjustable between - 1999 and H5CL value ). | 0 |
| HSCL | Upper scale value. ( Adjustable between L.5CL and 4000 value ). | 2000 |
| OUTPUT CONTROL PARAMETERS |  | Initial Value |
| o.5Et | Output set value. ( Adjustable between L.SEL and H.SCL). | 2000 |
| 0.435 | Output hysteresis value. ( Adjustable between ' and 200 ). | 2 |
| o.5t8 | Output status. (oFF: Output not active, Lo: Becomes active below the setpoint output value, $\boldsymbol{H} \boldsymbol{l}$ : Becomes active above the setpoint output value). | ofr |
| o.Pon | Required relay-on delay time in order to set output to active state after power-up. ( Adjustable between 0 and 99 minutes ). | $01: 00$ |
| o.ton | Output relay-on delay time. ( Adjustable between 0 and 99 minutes ). |  |
| o.tof | Output relay-off delay time. ( Adjustable between 0 and 99 minutes ). | 0 1:00 |
| ALARM CONTROL PARAMETERS |  | Initial Value |
| R.5Et | Alarm set value. (Adjustable between L .5 LL and HSLCL ). | 2000 |
| RH3S | Alarm hysteresis value. ( Adjustable between ' and 200 ). | 2 |
| Rtcyp | Alarm type. ( $\operatorname{nd} \mathcal{E}$ : Independent alarm, $d E$ : Deviation alarm, $b$ R $\cap$ d: Band alarm) | ind $E$ |
| R.5t 8 | Alarm condition. (oFF:Alarm not active. For independent or deviation alarm, $\mathrm{L} a$ : Alarm is active below the set value, $H:$ : Alarm is active above the set value. For band alarm, $b, H_{1}$ : Activated in "in-band", bo. $H_{1}$ : Activated in "out-band".) | of $F$ |
| RPon | Required relay-on delay time in order to set alarm output to active state after power-up. ( Adjustable between 0 and 99 minutes ). | 01:00 |
| Rton | Alarm output relay-on delay time. ( Adjustable between 0 and 99 minutes ). | 01:00 |
| Rt of | Alarm output relay-off delay time. ( Adjustable between 0 and 99 minutes ). | 0 1:00 |
| RS485 MODBUS COMMUNICATION PARAMETERS |  | Initial Value |
| Rodr 5 | Slave device address. ( Adjustable between 1 and 247) | 1 |
| bRU' | Baudrate. (Can be adjusted as ; ofF, 1200, 2400, 4800, 9600, 9200 kbps ) | 9500 |


| MODBUS ADDRESS MAP |  |  |  |  |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
| HOLDING REGISTERS |  |  |  |  |  |
| Holding Register Addresses |  | Data <br> Type | Data Content | ParameterName | Read / Write Permission |
| Decimal | Hex |  |  |  |  |
| 0000d | 0x0000 | word | Input type selection. $0=0-20 ; 1=4-20 ; 2=0-1 ; 3=0-10$ | LSP | R W |
| 0001d | 0x0001 | word |  | rite | R W |
| 0002d | 0x0002 | word | Indicator locking parameter. $0=n \circ \cap E ; 1=L \circ ; 2=H$, | hoid | R W |
| 0003d | 0x0003 | word | Decimal point. $0=x ; 1=x . x ; 2=x . x x ; 3=x . x x x$ | d.Pnt | R W |
| 0004d | 0x0004 | word | Scale lower value. | L.5CL | R W |
| 0005d | 0x0005 | word | Scale upper value. | HSCL | R W |
| 0006d | 0x0006 | word | Output set value. | o. $5 E t$ | R W |
| 0007d | 0x0007 | word | Output hysteresis value. | 0.4 HS | R W |
| 0008d | 0x0008 | word | Output condition. ( $0=0 \% F_{, 1=L} \quad$, 2= $=\boldsymbol{H}$ i) | o.5tR | R W |
| 0009d | 0x0009 | word | Required relay-on delay time in order to set output to active state after power-up. | o.Pon | R W |
| 0010d | 0x000A | word | Output relay-on delay time. | o.ton | R W |
| 0011d | 0x000B | word | Output relay-off delay time. | o.tof | R W |
| 0012d | 0x000C | word | Alarm set value. | R.5Et | R W |
| 0013d | 0x000D | word | Alarm hysteresis value. | RHYS | R W |
| 0014d | 0x000E | word |  | R.typ | R W |
| 0015d | 0x000F | word |  | R.5tR | R W |
| 0016d | 0x0010 | word | Required relay-on delay time in order to set alarm output to active state after power-up. | R.Pon | R W |
| 0017d | 0x0011 | word | Alarm output relay-on delay time. | Rton | R W |
| 0018d | 0x0012 | word | Alarm output relay-off delay time. | Rt of | R W |
| INPUT REGISTERS |  |  |  |  |  |
| Holding Register Addresses |  | Data <br> Type | Data Content | ParameterName | Read / Write Permission |
| Decimal | Hex |  |  |  |  |
| 0000d | 0x0000 | word | Measured value | - | Read Only |
| 0001d | 0x0001 | word | Minimum measured value | - | Read Only |
| 0002d | 0x0002 | word | Maximum measured value | - | Read Only |
| * Holding and Input Register parameters, which in integer type is defined as signed integer. Timing parameters are defined as seconds. (For example, 01:15 is defined as 75 seconds). |  |  |  |  |  |
| DISCRATE INPUTS |  |  |  |  |  |
| Holding Register Addresses |  | Data Type | Data Content | ParameterName | Read / Write Permission |
| Decimal | Hex |  |  |  |  |
| 0000d | 0x0000 | bit | OUT Control output condition. (0=OFF; $1=\mathrm{ON}$ ). | - | Read Only |
| 0001d | 0x0001 | bit | Alarm control output condition. ( $0=O F F ; 1=\mathrm{ON}$ ). | - | Read Only |
| COILS |  |  |  |  |  |
| Coil Addresses |  | Data Type | Data Content | ParameterName | Read / Write Permission |
| Decimal | Hex |  |  |  |  |
| 0000d | 0x0000 | bit | Indicator configuration ofF=Pr. $[5, \mathrm{ON}=$ Pr.U'U | dSP.L | R W |
| 0001d | 0x0001 | bit |  | [RLLE | R W |



[^0]* Applies to devices with Modbus function.


[^0]:    Termination should be accomplished by
    attaching 120 Ohm resistors to the start
    and at the end of the communication line.

